

On distances, paths and connections for hyperspectral image segmentation

Guillaume Noyel, Jesus Angulo, Dominique Jeulin

`{guillaume.noyel, jesus.angulo, dominique.jeulin}@ensmp.fr`

Centre de Morphologie Mathématique

Ecole des Mines de Paris

35, rue Saint-Honoré, 77305 Fontainebleau cedex - France

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Hyperspectral image

Definition

Hyperspectral image: at each point x_i is associated a vector with values in spectrum, time, wavelength, or associated to an index j .

$$\mathbf{f}_\lambda : \begin{cases} E & \rightarrow \mathcal{T}^L \text{ with } E \subset \mathbb{R}^2, \mathcal{T} \subset \mathbb{R} \\ x & \rightarrow \mathbf{f}_\lambda(x) = (f_{\lambda_1}(x), f_{\lambda_2}(x), \dots, f_{\lambda_L}(x)) \end{cases}$$

$f_{\lambda_j} \setminus j \in \{1, 2, \dots, L\}$ is a channel (L is the number of channels)

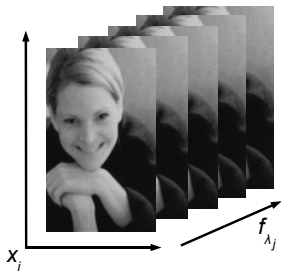


Image source: Spectral Database,
University of Joensuu Color Group,
<http://spectral.joensuu.fi/>

Spectral image: 400 nm to 700 nm 5 nm

Image size : $45 \times 76 \times 61$

Hyperspectral image

Image woman face in wavelength ($152 \times 91 \times 61$)



channels $\lambda = [400 : 5 : 700]$ nm

Quasi-flat zones

Definition: Quasi-flat zones or λ -flat zones (λ -FZ)

Given a distance $d : \mathcal{T}^L \times \mathcal{T}^L \rightarrow \mathbb{R}^+$, two points $x, y \in E$ belongs to the same quasi-flat zone of an hyperspectral image \mathbf{f}_λ if and only if there is a path $(p_0, p_1, \dots, p_n) \in E^n$ such as $p_0 = x$ and $p_n = y$ and, if, for all i , $(p_i, p_{i+1}) \in E^2$ are neighbours and $d(\mathbf{f}_\lambda(p_i), \mathbf{f}_\lambda(p_{i+1})) \leq \lambda$, with $\lambda \in \mathbb{R}^+$.

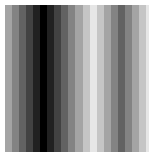
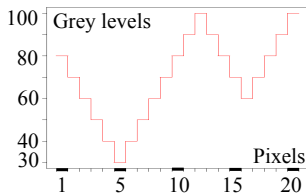


Image
(21 × 21)



Row profile



λ -FZ
 $\lambda = 9,9$
21 zones



λ -FZ
 $\lambda = 10$
1 zone

Issue

Limitations of λ -Flat Zones: they are very sensitive to parameter λ because only local information is taken into account.

Aim of the study: To solve this effect we introduce finer partitions of each λ -FZ using regional information.

Starting with an initial partition by λ -FZ with a non critical high value of λ that leads to a sub-segmentation, a second segmentation is performed based on two new connections:

- η -Bounded Regions: η -BR
- μ -Geodesic Balls: μ -GB

The corresponding algorithms are founded on seed-based region growing inside the λ -FZ.

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Definitions

Definition (Partition)

Let E be an arbitrary set. A partition \mathcal{D} of E is a mapping $x \rightarrow D(x)$ from E into $\mathcal{P}(E)$ such that: (i) for all $x \in E$: $x \in D(x)$, (ii) for all $x, y \in E$: $D(x) = D(y)$ or $D(x) \cap D(y) = \emptyset$. $D(x)$ is called the class of the partition of origin x .

The set of partitions of an arbitrary set E is ordered as follows.

Definition (Order of partitions)

A partition \mathcal{A} is said to be finer (resp. coarser) than a partition \mathcal{B} , $\mathcal{A} \leq \mathcal{B}$ (resp. $\mathcal{A} \geq \mathcal{B}$), when each class of \mathcal{A} is included in a class of \mathcal{B} .

This leads to the notion of ordered hierarchy of partitions $\prod_{i=1}^N \mathcal{D}_i$, such that $\mathcal{D}_i \leq \mathcal{D}_{i+1}$, and even to a complete lattice [Serra(2006)].

Definitions

To solve this effect (too high sensitivity of λ parameter), we create finer partitions of each λ -FZ. These partitions are defined with connections.

Definition (Connection)

Let E be an arbitrary non empty set. We call connected class or connection \mathcal{C} any family in $\mathcal{P}(E)$ such that: (0) $\emptyset \in \mathcal{C}$, (i) for all $x \in E$, $\{x\} \in \mathcal{C}$, (ii) for each family $C_i, i \in I$ in \mathcal{C} , $\cap_i C_i \neq \emptyset$ implies $\cup_i C_i \in \mathcal{C}$. Any set C of a connected class \mathcal{C} is said to be connected.

Vectorial median

Definition (Vectorial median)

A vectorial median of a set $R \subset E$ is any value $\mathbf{f}_\lambda(k)$ in the set at point $k \in R$ such as:

$$k = \operatorname{argmin}_{p \in R} \sum_{i/x_i \in R} d(\mathbf{f}_\lambda(p), \mathbf{f}_\lambda(x_i)) = \operatorname{argmin}_{p \in R} \delta_R(\mathbf{f}_\lambda(p)) \quad (1)$$

i.e. "one of the points which minimize the sum of distances to the others".

δ_R : ascending ordered list based on the cumulative distance (of each point of R to the others).

The first element of the list δ_R is the vectorial median (the last element is considered as the anti-median).

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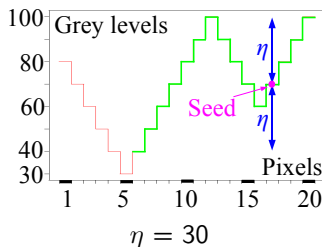
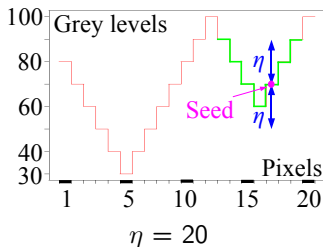
η -bounded regions η -BR

Comparison with λ -FZ

For λ -FZ, a hiker starting from one point only deals with the local slope and not with the difference in altitude on the λ -flat zones.

Principle for η -BR

Considering the difference in altitude, a hiker starting from one point x has a walk restricted to a ball of diameter $2 \times \eta$ centered on x inside a λ -FZ.



η -bounded regions η -BR

Definition (η -bounded connection)

Given an hyperspectral image $\mathbf{f}_\lambda(x)$ and its initial partition based on λ -flat zones, λFZ , where λFZ_i is the connected class i and $R_i \subseteq E$ (with cardinal K) is the set of points p_k , $k = 0, 1, 2, \dots, K - 1$, that belongs to the class i . Let p_0 be a point of R_i , named the center of class i , and let $\eta \in \mathbb{R}^+$ be a positive value. A point p_k belongs to the η -connected component centered at p_0 , denoted $\eta BR_i^{p_0}$, if and only if $d(\mathbf{f}_\lambda(p_0), \mathbf{f}_\lambda(p_k)) \leq \eta$ and p_0 and p_k are connected.

Seed (center of the class): 1st non assigned-point of ascending ordered list based on the cumulative distance δ_R in a λ -FZ.

η -bounded regions η -BR

Construction of η -BR

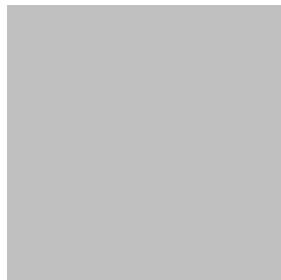
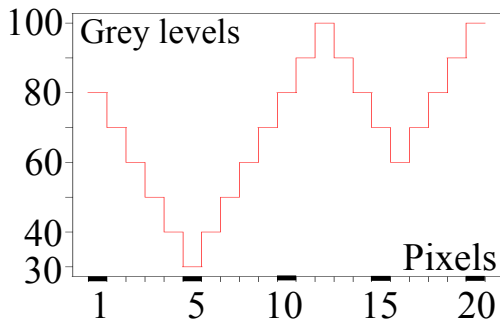
For each class λFZ_i the method is iterated with different centers p_j ($j = 0, 1, \dots, J$) until: $\cup_{j=0}^J \eta BR_i^{p_j} = \lambda FZ_i$, $\cap_{j=0}^J \eta BR_i^{p_j} = \emptyset$ where the η -bounded regions are connected.

Properties of η -BR

- Each seed p_j belongs to $\lambda FZ_i \setminus \cup_{l=0}^{j-1} \eta BR_i^{p_l}$.
- $\forall x \in E, \eta BR(x) \leq \lambda FZ(x)$

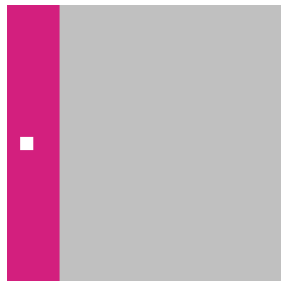
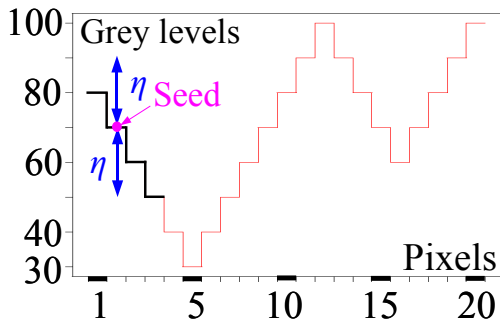
η -bounded regions η -BR

$$\lambda = 10, \eta = 20$$



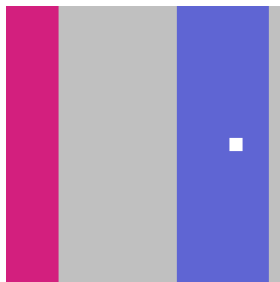
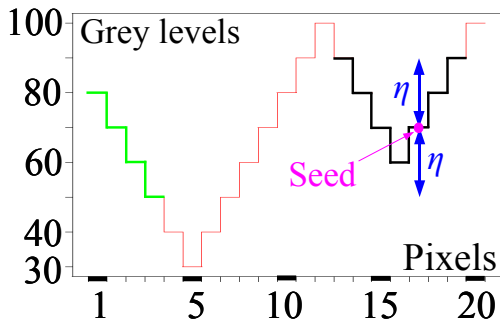
η -bounded regions η -BR

$$\lambda = 10, \eta = 20$$



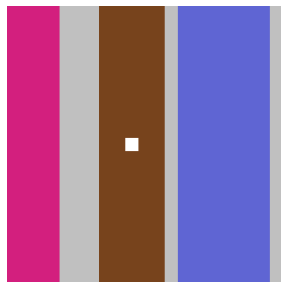
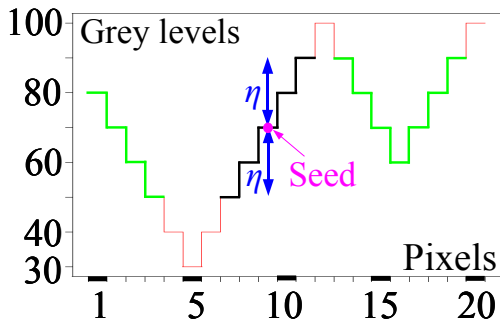
η -bounded regions η -BR

$$\lambda = 10, \quad \eta = 20$$



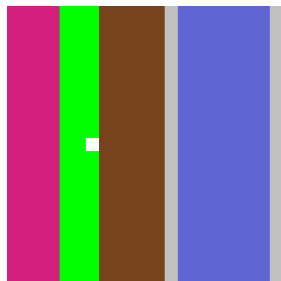
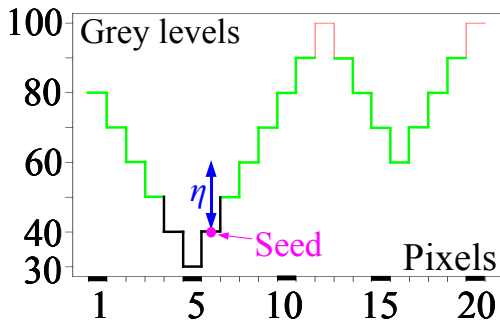
η -bounded regions η -BR

$$\lambda = 10, \eta = 20$$



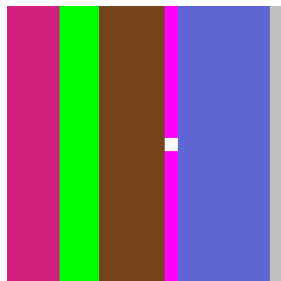
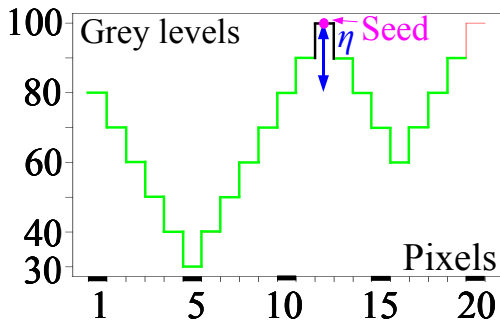
η -bounded regions η -BR

$$\lambda = 10, \eta = 20$$



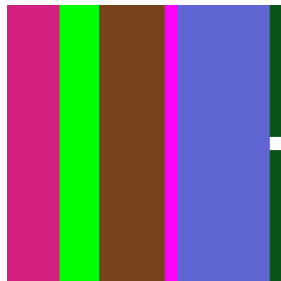
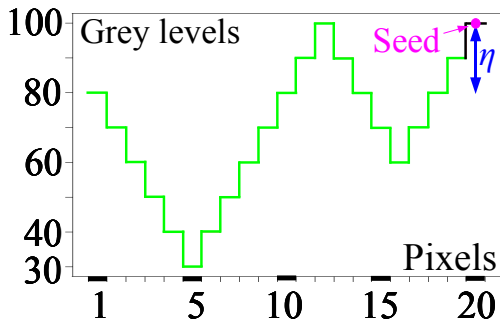
η -bounded regions η -BR

$$\lambda = 10, \quad \eta = 20$$



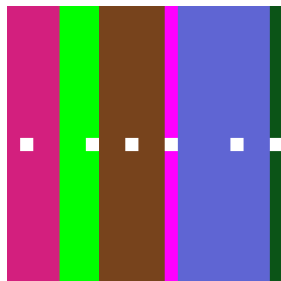
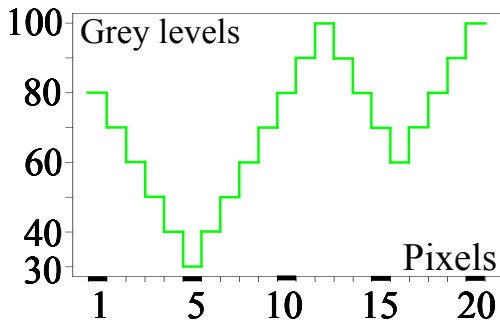
η -bounded regions η -BR

$$\lambda = 10, \quad \eta = 20$$



η -bounded regions η -BR

$$\lambda = 10, \quad \eta = 20$$

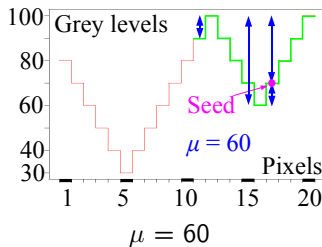
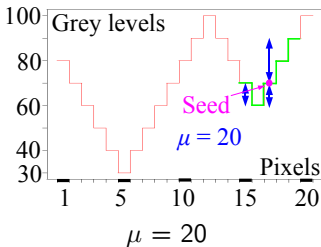


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μ -geodesic balls μ -GB

Principle of μ -GB

A hiker starting from one point k has a walk restricted by a cumulative difference in altitude less than μ , inside a λ -FZ.



μ -geodesic balls μ -GB

Definition (μ -geodesic connection)

Given an hyperspectral image $\mathbf{f}_\lambda(x)$ and its initial partition based on λ -flat zones, λFZ , where λFZ_i is the connected class i and $R_i \subseteq E$ (with cardinal K) is the set of points p_k , $k = 0, 1, 2, \dots, K - 1$, that belongs to the class i . Let p_0 be a point of R_i , named the center of class i , and let $\mu \in \mathbb{R}^+$ be a positive value. A point p_k belongs to the μ -connected component centered at p_0 , denoted $\mu GB_i^{p_0}$ if and only if $d_{geo}(\mathbf{f}_\lambda(p_0), \mathbf{f}_\lambda(p_k)) \leq \mu$.

Seed (center of the class): 1st non assigned-point of ascending ordered list based on the cumulative distance δ_R in a λ -FZ.

μ -geodesic balls μ -GB

Construction of μ -GB

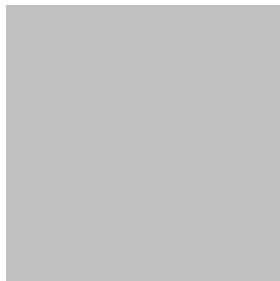
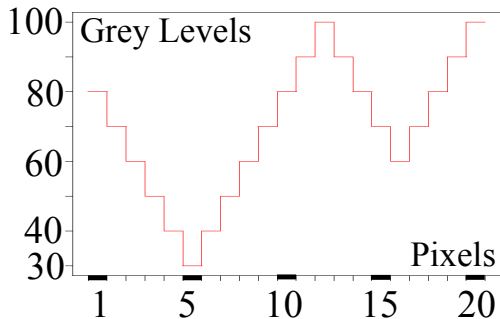
μ -geodesic balls are built as η -bounded regions, except that from each seed the geodesic ball is computed inside the λ -FZ.

Properties of μ -GB

- Each seed p_j belongs to $\lambda FZ_i \setminus \cup_{l=0}^{j-1} \mu GB_i^{p_l}$.
- $\forall x \in E, \mu GB(x) \leq \lambda FZ(x)$
- we have a regional control of the “geodesic size” of the classes

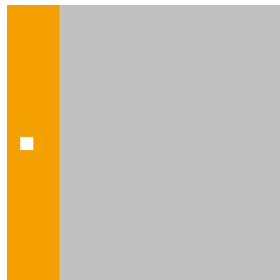
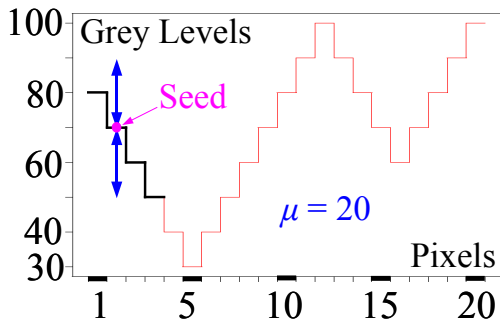
μ -geodesic balls μ -GB

$$\lambda = 10, \mu = 20$$



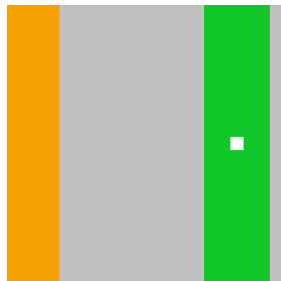
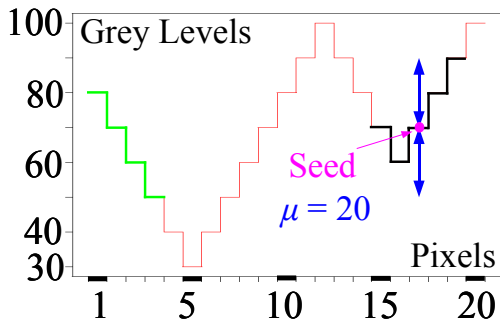
μ -geodesic balls μ -GB

$$\lambda = 10, \mu = 20$$



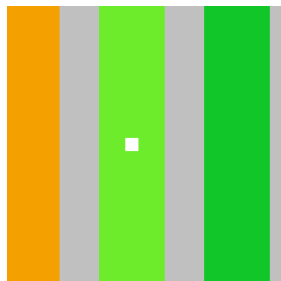
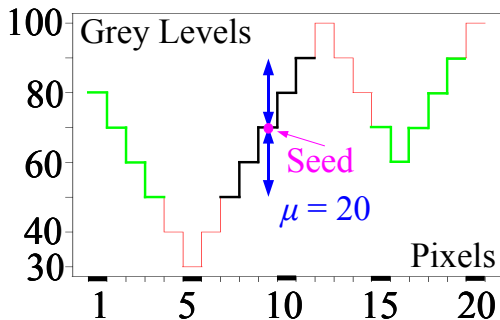
μ -geodesic balls μ -GB

$$\lambda = 10, \mu = 20$$



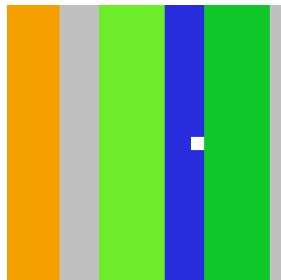
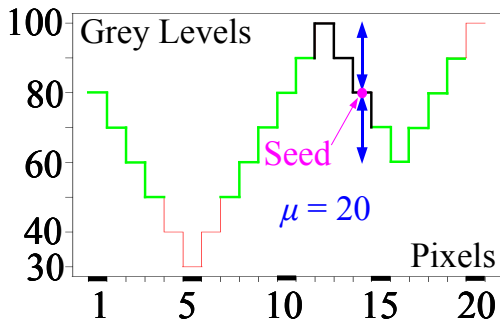
μ -geodesic balls μ -GB

$$\lambda = 10, \mu = 20$$



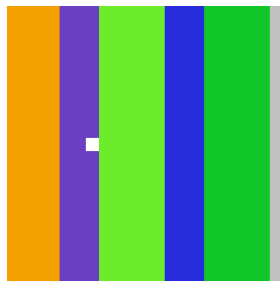
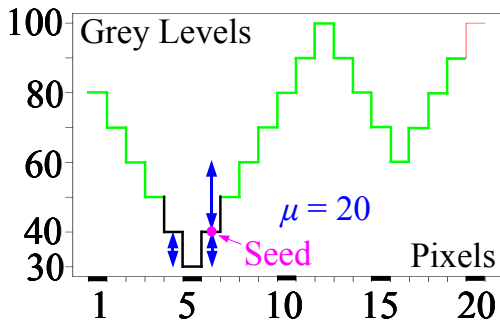
μ -geodesic balls μ -GB

$$\lambda = 10, \mu = 20$$



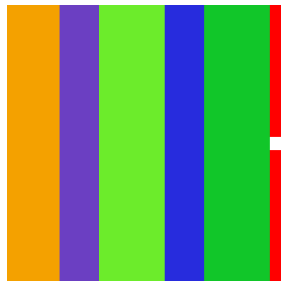
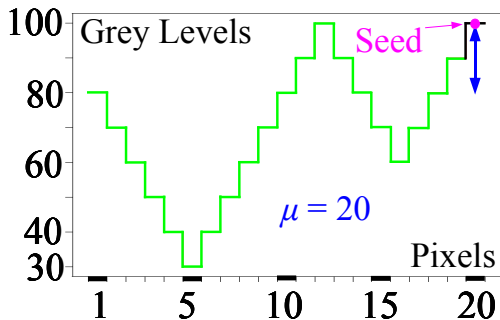
μ -geodesic balls μ -GB

$$\lambda = 10, \mu = 20$$



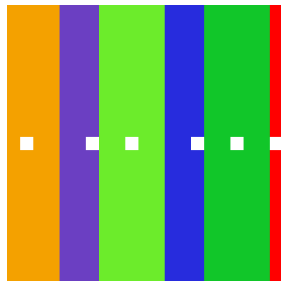
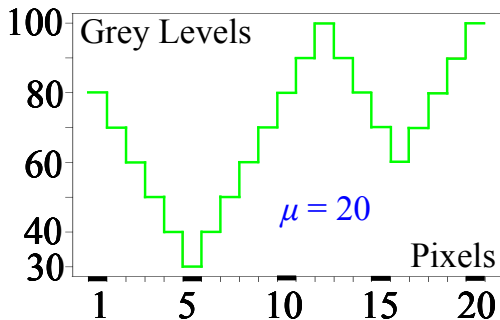
μ -geodesic balls μ -GB

$$\lambda = 10, \mu = 20$$



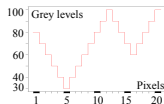
μ -geodesic balls μ -GB

$$\lambda = 10, \mu = 20$$



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Comparison between η -BR and μ -GB



Row profile



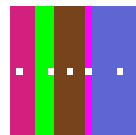
λ -FZ
 $\lambda = 10$



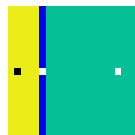
η -BR
 $\eta = 0$



η -BR
 $\eta = 10$



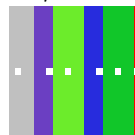
η -BR
 $\eta = 20$



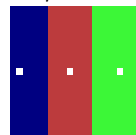
η -BR
 $\eta = 30$



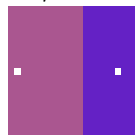
μ -GB
 $\mu = 0$



μ -GB
 $\mu = 20$

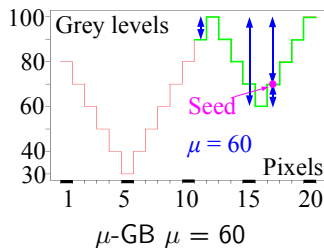
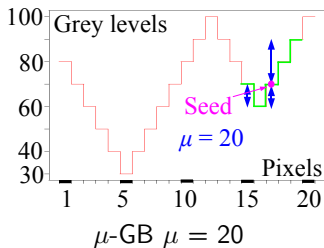
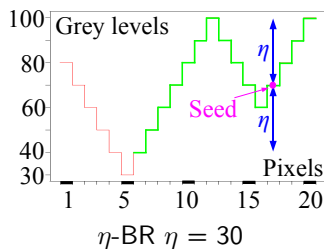
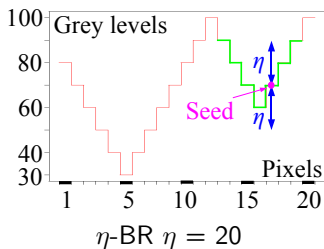


μ -GB
 $\mu = 40$



μ -GB
 $\mu = 100$

Comparison between η -BR and μ -GB



Comparison between η -BR and μ -GB

	η -BR	μ -GB
Sensitivity to bumps (and hollows)	+	−
Control of the size of the region	−	+

Results in image space

Generalization to hyperspectral images:

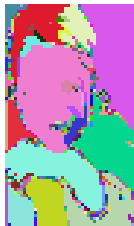
- use of vector distances (Chi-Squared, Euclidean)
- seed: vectorial median and not the minima or the maxima which does not exist.



$f_{\lambda_{61}}$
($45 \times 76 \times 61$)



λ -FZ
 $\lambda = 0.003$



λ -FZ
 $\lambda = 0.004$



λ -FZ
 $\lambda = 0.005$



λ -FZ
 $\lambda = 0.006$

Chi-squared distance is used d_{χ^2} .

Results in image space



λ -FZ
 $\lambda = 0.005$



η -BR
 $\eta = 0.007$



η -BR
 $\eta = 0.009$



η -BR
 $\eta = 0.011$



η -BR
 $\eta = 0.02$



μ -GB
 $\mu = 0.01$



μ -GB
 $\mu = 0.02$



μ -GB
 $\mu = 0.03$



μ -GB
 $\mu = 0.05$

Results in image space

Seed: anti-median. Few changes are observed.
⇒ robustness of the method to the seeds choice.



λ -FZ
 $\lambda = 0.005$



η -BR
 $\eta = 0.009$



η -BR
 $\eta = 0.011$



μ -GB
 $\mu = 0.02$



μ -GB
 $\mu = 0.03$

Chi-squared distance is used d_{χ^2} .

Results in factor space

FCA (Factor Correspondence Analysis) [Benzécri(1973)]

Factor axes filtered by leveling (structuring element squared 3×3).



$c_{\alpha_1}^f$
inertia 87.8%



$c_{\alpha_2}^f$
inertia 10.2%



$c_{\alpha_3}^f$
inertia 1.5%

Results in factor space



λ -FZ
 $\lambda = 0.04$



η -BR
 $\eta = 0.1$



η -BR
 $\eta = 0.15$



μ -GB
 $\mu = 0.1$



μ -GB
 $\mu = 0.3$

Euclidean distance is used d_E .

Some other results on a satellite image



f_{λ_1} blue
©CNES



f_{λ_2} green
©CNES



f_{λ_3} red
©CNES



f_{λ_4} proche IR
©CNES



f_{λ_5} panchrom.
©CNES



synthetic RGB

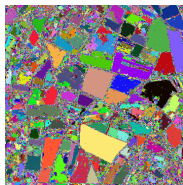
Image "Roujan" $365 \times 365 \times 5$ pixels. Resolution 0.70 meters.
Source: CNES (French space agency) + Pr. G. Flouzat (Laboratoire de Télédétection à Haute Résolution, Toulouse 3)

Some other results on a satellite image

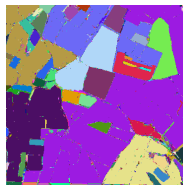
Image space: Chi-squared distance is used d_{χ^2} .



synthetic RGB



λ -FZ
 $\lambda = 0.005$



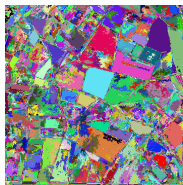
λ -FZ
 $\lambda = 0.015$

Some other results on a satellite image

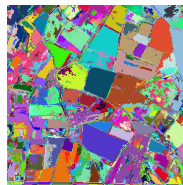
Image space: Chi-squared distance is used d_{χ^2} .



synthetic RGB



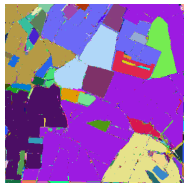
η -BR
 $\eta = 0.02$



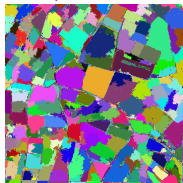
η -BR
 $\eta = 0.03$



η -BR
 $\eta = 0.04$



λ -FZ
 $\lambda = 0.015$



μ -GB
 $\mu = 0.1$



μ -GB
 $\mu = 0.2$



μ -GB
 $\mu = 0.3$

Application fields

- Definition of homogeneous regions useful as markers for watershed segmentation
- Detection and characterization of textured regions

- 1 Introduction
- 2 General notions
- 3 η -bounded regions
- 4 μ -geodesic balls
- 5 Results and discussions
- 6 Conclusions and perspectives

Conclusions and perspectives

- η -BR and μ -GB improve λ -FZ (local information) by introduction of regional information.
- η -bounded connection and μ -geodesic connection are connections of 2^{nd} order because they are included in λ -FZ.
- The approach consists in selecting a sufficiently high parameter λ to obtain first a sub-segmentation.
- These connections lead to a pyramid of partition which is not an ordered pyramid.
- They are the generalization of the jump connection [Serra(1999)] with the difference that the seeds p_j cannot be the minima or maxima. Seed: vector median.
- Perspective: to select locally for each λ -FZ the value for η or μ .

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