#### Locally finite spaces and the join operator

Erik Melin

Uppsala University, Department of Mathematics

ISMM Rio de Janeiro, October 11, 2007



#### What is our goal?

• We want to understand the local structure of digital topological spaces.

## What is our goal?

- We want to understand the local structure of digital topological spaces.
- We show that such a space can be uniquely decomposed as a join of indecomposable spaces.

## What is our goal?

- We want to understand the local structure of digital topological spaces.
- We show that such a space can be uniquely decomposed as a join of indecomposable spaces.
- A long-term goal is to understand global structure. What are the possibilities to introduce digital manifolds?

# Why? What is the relation to mathematical morphology?

• Morphological operations are (sometimes) performed on digital images.

# Why? What is the relation to mathematical morphology?

- Morphological operations are (sometimes) performed on digital images.
- Digital images are (sometimes) topological spaces. We might deal with complicated spaces.

# Why? What is the relation to mathematical morphology?

- Morphological operations are (sometimes) performed on digital images.
- Digital images are (sometimes) topological spaces. We might deal with complicated spaces.
- We would (perhaps) like morphological operations compatible with the structure of the spaces, for example connectivity or closure operations.
  The formalism and the theorems proved about this formalism could be a useful tool.

Let X, Y, Z etc be smallest-neighborhood space. The *join* of X and Y is denoted  $X \vee Y$ . We have (technical details omitted):

Let X, Y, Z etc be smallest-neighborhood space. The *join* of X and Y is denoted  $X \vee Y$ . We have (technical details omitted):

#### Theorem (Uniqueness)

If  $X = Y \lor Z$  and  $X = \tilde{Y} \lor \tilde{Z}$ , and  $Y, \tilde{Y}$  are indecomposable, then  $Y = \tilde{Y}$  and  $Z = \tilde{Z}$ .

Let X, Y, Z etc be smallest-neighborhood space. The *join* of X and Y is denoted  $X \vee Y$ . We have (technical details omitted):

#### Theorem (Uniqueness)

If  $X = Y \lor Z$  and  $X = \tilde{Y} \lor \tilde{Z}$ , and  $Y, \tilde{Y}$  are indecomposable, then  $Y = \tilde{Y}$  and  $Z = \tilde{Z}$ .

#### Theorem (Decomposition)

A locally finite space can be written in a unique way as  $Y_1 \vee Y_2 \vee \cdots \vee Y_n$ , where each  $Y_i$  is indecomposable.

Let X, Y, Z etc be smallest-neighborhood space. The *join* of X and Y is denoted  $X \vee Y$ . We have (technical details omitted):

#### Theorem (Uniqueness)

If  $X = Y \lor Z$  and  $X = \tilde{Y} \lor \tilde{Z}$ , and  $Y, \tilde{Y}$  are indecomposable, then  $Y = \tilde{Y}$  and  $Z = \tilde{Z}$ .

#### Theorem (Decomposition)

A locally finite space can be written in a unique way as  $Y_1 \vee Y_2 \vee \cdots \vee Y_n$ , where each  $Y_i$  is indecomposable.

#### Theorem (Cancellation)

If  $A \lor X$  and  $B \lor X$  are homeomorphic, then A and B are homeomorphic.

Let X be a set and  $\mathcal{T} \subseteq \mathcal{P}(X)$  a family of subsets.

Let X be a set and  $\mathcal{T} \subseteq \mathcal{P}(X)$  a family of subsets.

• X and  $\varnothing$  belong to T.

Let X be a set and  $\mathcal{T} \subseteq \mathcal{P}(X)$  a family of subsets.

- X and  $\varnothing$  belong to T.
- $A_i \in \mathcal{T}, i \in I \Longrightarrow \bigcup_{i \in I} A_i \in \mathcal{T}.$

Let X be a set and  $\mathcal{T} \subseteq \mathcal{P}(X)$  a family of subsets.

- X and  $\varnothing$  belong to T.
- $A_i \in \mathcal{T}, i \in I \Longrightarrow \bigcup_{i \in I} A_i \in \mathcal{T}.$
- $A_i \in \mathcal{T}, i \in I \Longrightarrow \bigcap_{i \in I} A_i \in \mathcal{T}$  no restriction.

Let X be a set and  $T \subseteq \mathcal{P}(X)$  a family of subsets.

- X and  $\varnothing$  belong to T.
- $A_i \in \mathcal{T}, i \in I \Longrightarrow \bigcup_{i \in I} A_i \in \mathcal{T}.$
- $A_i \in \mathcal{T}, i \in I \Longrightarrow \bigcap_{i \in I} A_i \in \mathcal{T}$  no restriction.

The spaces are called **smallest-neighborhood spaces** or **Alexandrov spaces**.

$$\mathcal{N}(x) = \bigcap (A; A \subseteq X \text{ is open and } x \in A).$$

$$\mathcal{N}(x) = \bigcap (A; A \subseteq X \text{ is open and } x \in A).$$

$$\mathscr{C}(x) = \bigcap (A; A \subseteq X \text{ is closed and } x \in A).$$

$$\mathcal{N}(x) = \bigcap (A; A \subseteq X \text{ is open and } x \in A).$$

$$\mathscr{C}(x) = \bigcap (A; A \subseteq X \text{ is closed and } x \in A).$$

Let 
$$AN(x) = \mathcal{C}(x) \cup \mathcal{N}(x)$$
 and  $\mathcal{A}(x) = AN(x) \setminus \{x\}$ .

Let *X* be a topological space, and  $x \in X$ . Consider:

$$\mathcal{N}(x) = \bigcap (A; A \subseteq X \text{ is open and } x \in A).$$

$$\mathscr{C}(x) = \bigcap (A; A \subseteq X \text{ is closed and } x \in A).$$

Let 
$$AN(x) = \mathscr{C}(x) \cup \mathscr{N}(x)$$
 and  $\mathscr{A}(x) = AN(x) \setminus \{x\}$ .

• If X a smallest-neighborhood space, then  $\mathcal{N}(x)$  is open.

$$\mathcal{N}(x) = \bigcap (A; A \subseteq X \text{ is open and } x \in A).$$

$$\mathscr{C}(x) = \bigcap (A; A \subseteq X \text{ is closed and } x \in A).$$

Let 
$$AN(x) = \mathcal{C}(x) \cup \mathcal{N}(x)$$
 and  $\mathcal{A}(x) = AN(x) \setminus \{x\}$ .

- If X a smallest-neighborhood space, then  $\mathcal{N}(x)$  is open.
- $\mathscr{C}(x)$  is always closed.

$$\mathcal{N}(x) = \bigcap (A; A \subseteq X \text{ is open and } x \in A).$$

$$\mathscr{C}(x) = \bigcap (A; A \subseteq X \text{ is closed and } x \in A).$$

Let 
$$AN(x) = \mathcal{C}(x) \cup \mathcal{N}(x)$$
 and  $\mathcal{A}(x) = AN(x) \setminus \{x\}$ .

- If X a smallest-neighborhood space, then  $\mathcal{N}(x)$  is open.
- $\mathscr{C}(x)$  is always closed.
- $\{x,y\}$  connected if and only if  $x \in AN(y)$ .

Let us call a smallest-neighborhood space **locally finite** if AN(x) is a finite set for every point x. This condition excludes strange spaces, compare with the property *paracompactness* in topology.

Let us call a smallest-neighborhood space **locally finite** if AN(x) is a finite set for every point x. This condition excludes strange spaces, compare with the property *paracompactness* in topology.

The space is called **locally countable** if each AN(x) is countable.

Let us call a smallest-neighborhood space **locally finite** if AN(x) is a finite set for every point x. This condition excludes strange spaces, compare with the property *paracompactness* in topology.

The space is called **locally countable** if each AN(x) is countable.

#### Theorem

If X is locally finite and connected, then X is countable.

Let us call a smallest-neighborhood space **locally finite** if AN(x) is a finite set for every point x. This condition excludes strange spaces, compare with the property *paracompactness* in topology.

The space is called **locally countable** if each AN(x) is countable.

#### Theorem

If X is locally finite and connected, then X is countable.

#### Theorem

A space X is countable if and only if it is locally countable and has countably many connectivity components.

## Dense sets in smallest-neighborhood spaces

#### Theorem

If X is locally finite, then the set of open points in X is dense in X.

# Dense sets in smallest-neighborhood spaces

#### Theorem

If X is locally finite, then the set of open points in X is dense in X.

If a space is not locally finite, then this need not be the case.

#### Example

Consider  $\mathbb{Z}$  equipped with the open sets  $]-\infty,m],\ m\in\mathbb{Z}$ . This space has no open point.

# Proof of countability

A **Khalimsky arc** in X is the homeomorphic image of a Khalimsky interval,  $[a,b]_{\mathbb{Z}}$ . The **length** of an arc is the number of points minus 1. The arc metric on X (provided X is  $T_0$  and connected) is the following:

$$\rho(x,y) = \min(\text{Length}(A); A \text{ is a Kh. arc containing } x \text{ and } y.)$$

# Proof of countability

A **Khalimsky arc** in X is the homeomorphic image of a Khalimsky interval,  $[a,b]_{\mathbb{Z}}$ . The **length** of an arc is the number of points minus 1. The arc metric on X (provided X is  $T_0$  and connected) is the following:

$$\rho(x,y) = \min(\text{Length}(A); A \text{ is a Kh. arc containing } x \text{ and } y.)$$

Now fix a point  $x \in X$ , and consider balls  $B_m = \{y \in X; \ \rho(x,y) \leqslant m\}$ , m = 0,2... (Some technicalities needed of X is not  $T_0$ ).

# Proof of countability

A **Khalimsky arc** in X is the homeomorphic image of a Khalimsky interval,  $[a,b]_{\mathbb{Z}}$ . The **length** of an arc is the number of points minus 1. The arc metric on X (provided X is  $T_0$  and connected) is the following:

$$\rho(x,y) = \min(\text{Length}(A); A \text{ is a Kh. arc containing } x \text{ and } y.)$$

Now fix a point  $x \in X$ , and consider balls  $B_m = \{y \in X; \ \rho(x,y) \leqslant m\}$ , m = 0,2... (Some technicalities needed of X is not  $T_0$ ).

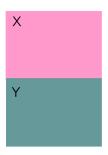
Every ball is finite, and  $X = \bigcup_{m \in \mathbb{Z}} B_m$ .

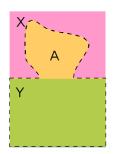
# The join of two spaces

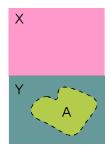
Let *X* and *Y* be topological spaces.

The join,  $X \vee Y$ , is the disjoint (set) union where  $A \subset X \dot{\cup} Y$  is declared to be open if:

- $A \cap X$  open in X,  $A \cap Y = Y$ , or
- $A \cap Y$  open in Y,  $A \cap X = \emptyset$ .







# The join in smallest-neighborhood spaces

Suppose  $Z = X \lor Y$  where X and Y are smallest-neighborhood spaces. Then

- $\mathcal{N}_Z(x) = \mathcal{N}_X(x) \cup Y$  if  $x \in X$ .
- $\mathcal{N}_{Z}(y) = \mathcal{N}_{Y}(y)$  if  $y \in Y$ .

# The join in smallest-neighborhood spaces

Suppose  $Z = X \lor Y$  where X and Y are smallest-neighborhood spaces. Then

- $\mathcal{N}_Z(x) = \mathcal{N}_X(x) \cup Y$  if  $x \in X$ .
- $\mathcal{N}_Z(y) = \mathcal{N}_Y(y)$  if  $y \in Y$ .

Dually, the closures become.

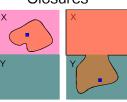
- $\mathscr{C}_Z(x) = \mathscr{C}_Y(x)$  if  $x \in X$ .
- $\mathscr{C}_Z(y) = \mathscr{C}_X(y) \cup X$  if  $y \in Y$ .

# Neighborhoods





#### Closures



## Properties of the join operator

The following properties are straightforward to prove.

#### Properties of the join operator

The following properties are straightforward to prove.

•  $\forall X : X = X \lor \emptyset = \emptyset \lor X$  (has identity).

# Properties of the join operator

The following properties are straightforward to prove.

- $\forall X : X = X \lor \emptyset = \emptyset \lor X$  (has identity).
- $\exists X, Y \colon X \lor Y \neq Y \lor X$  (not commutative).

# Properties of the join operator

The following properties are straightforward to prove.

- $\forall X : X = X \lor \emptyset = \emptyset \lor X$  (has identity).
- $\exists X, Y \colon X \lor Y \neq Y \lor X$  (not commutative).
- $\forall X, Y, Z : (X \lor Y) \lor Z = X \lor (Y \lor Z)$  (associative).

# Properties of the join operator

The following properties are straightforward to prove.

- $\forall X : X = X \lor \emptyset = \emptyset \lor X$  (has identity).
- $\exists X, Y : X \lor Y \neq Y \lor X$  (not commutative).
- $\forall X, Y, Z : (X \lor Y) \lor Z = X \lor (Y \lor Z)$  (associative).
- $X \vee Y$  is always connected, provided  $X \neq \emptyset$  and  $Y \neq \emptyset$ .

# Decomposable spaces

### Definition

*Z* is called **indecomposable** if  $Z = X \lor Y$  implies  $X = \emptyset$  or  $Y = \emptyset$ . Otherwise *Z* is called **decomposable**.

# Decomposable spaces

### Definition

*Z* is called **indecomposable** if  $Z = X \lor Y$  implies  $X = \emptyset$  or  $Y = \emptyset$ . Otherwise *Z* is called **decomposable**.

### Example

The Khalimsky interval  $I = [1,3]_{\mathbb{Z}}$  is decomposable.  $I = \{2\} \vee \{1,3\}$  where the factors have the discrete topology.

# Decomposable spaces

### Definition

*Z* is called **indecomposable** if  $Z = X \lor Y$  implies  $X = \emptyset$  or  $Y = \emptyset$ . Otherwise *Z* is called **decomposable**.

### Example

The Khalimsky interval  $I = [1,3]_{\mathbb{Z}}$  is decomposable.  $I = \{2\} \vee \{1,3\}$  where the factors have the discrete topology.

### Theorem (Uniqueness)

Suppose that Z is locally finite and  $T_0$ . If  $Z = X \vee Y$ ,  $Z = \tilde{X} \vee \tilde{Y}$  and if X,  $\tilde{X}$  are indecomposable, then  $X = \tilde{X}$  and  $Y = \tilde{Y}$ .

# Decomposable spaces continued

Can we somehow recognize indecomposable spaces?

# Decomposable spaces continued

Can we somehow recognize indecomposable spaces?

#### Theorem

Let *Z* be a smallest-neighborhood space. If *Z* is decomposable, then  $\rho(x,y) \leq 2$  for all  $x,y \in Z$ .

# Decomposable spaces continued

Can we somehow recognize indecomposable spaces?

#### Theorem

Let *Z* be a smallest-neighborhood space. If *Z* is decomposable, then  $\rho(x,y) \leqslant 2$  for all  $x,y \in Z$ .

### Example

The Khalimsky interval  $I = [1,4]_{\mathbb{Z}}$  is indecomposable.

Conclusion: The join is only of interest with a local perspective.

### Cancellation laws

It is not true, in general, that we from  $A \lor X \approx B \lor X$  can conclude that  $A \approx B$ . However, if X is locally finite, we have

#### Theorem

Let X be locally finite. Then for every smallest-neighborhood space A and B we have

$$A \lor X \approx B \lor X \implies A \approx B$$

and

$$X \lor A \approx X \lor B \implies A \approx B$$

### Some observations

### Claim

$$\mathscr{A}(x) = (\mathscr{C}(x) \setminus \{x\}) \vee (\mathscr{N}(x) \setminus \{x\})$$

### Some observations

### Claim

$$\mathscr{A}(x) = (\mathscr{C}(x) \setminus \{x\}) \vee (\mathscr{N}(x) \setminus \{x\})$$

### Claim

$$AN(x) = (\mathscr{C}(x) \setminus \{x\}) \vee \{x\} \vee (\mathscr{N}(x) \setminus \{x\})$$

### Some observations

#### Claim

$$\mathscr{A}(x) = (\mathscr{C}(x) \setminus \{x\}) \vee (\mathscr{N}(x) \setminus \{x\})$$

#### Claim

$$AN(x) = (\mathscr{C}(x) \setminus \{x\}) \vee \{x\} \vee (\mathscr{N}(x) \setminus \{x\})$$

Given  $x \in \mathbb{Z}^n$  (Khalimsky *n*-space), we have  $\mathcal{N}(x) \approx [-1, +1]^k$  and  $\mathcal{C}(x) \approx [0, 2]^l$ .

Understanding  $\mathcal{A}(x)$  directly is relatively complicated...

(The characterization of  $\mathbb{Z}^n$  can be found in Evako et al. (1996)) Note: Unique decomposition immediately gives uniqueness of dimension.

### Partial orders

Consider the Alexandrov-Birkhoff specialization order:

$$x \leq y \iff x \in \mathcal{N}(y) \iff y \in \mathcal{C}(x)$$

### Partial orders

Consider the Alexandrov-Birkhoff specialization order:

$$x \leq y \iff x \in \mathcal{N}(y) \iff y \in \mathcal{C}(x)$$

That is: 
$$\mathcal{N}(x) = \{y; \ y \leq x\}$$
 and  $\mathcal{C}(x) = \{y; \ y \geq x\}$ 

### Partial orders

Consider the Alexandrov–Birkhoff specialization order:

$$x \preccurlyeq y \iff x \in \mathcal{N}(y) \iff y \in \mathcal{C}(x)$$

That is:  $\mathcal{N}(x) = \{y; \ y \leq x\}$  and  $\mathcal{C}(x) = \{y; \ y \geq x\}$ Viewed as partial orders  $X \vee Y$  means X is placed on top of Y.

$$\mathscr{A}(x) = (\mathscr{C}(x) \cup \mathscr{N}(x)) \setminus \{x\} = \{y; \ y \succ x\} \cup \{y; \ y \prec x\}$$

The first claim follows. The second claim is similar.

Consider again the second claim:

$$AN(x) = (\mathscr{C}(x) \setminus \{x\}) \vee \{x\} \vee (\mathscr{N}(x) \setminus \{x\}).$$

Consider again the second claim:

$$AN(x) = (\mathscr{C}(x) \setminus \{x\}) \vee \{x\} \vee (\mathscr{N}(x) \setminus \{x\}).$$

If X is locally finite, then  $\mathcal{N}(x)$  is a finite set with a partial order. Therefore it has a minimal element m, i.e., for no  $y \in \mathcal{N}(x)$  is  $y \leq m$ .

Consider again the second claim:

$$AN(x) = (\mathscr{C}(x) \setminus \{x\}) \vee \{x\} \vee (\mathscr{N}(x) \setminus \{x\}).$$

If X is locally finite, then  $\mathcal{N}(x)$  is a finite set with a partial order. Therefore it has a minimal element m, i.e., for no  $y \in \mathcal{N}(x)$  is  $y \leq m$ .

But m is then minimal also in X, hence  $\{m\}$  is open.

Consider again the second claim:

$$AN(x) = (\mathscr{C}(x) \setminus \{x\}) \vee \{x\} \vee (\mathscr{N}(x) \setminus \{x\}).$$

If X is locally finite, then  $\mathcal{N}(x)$  is a finite set with a partial order. Therefore it has a minimal element m, i.e., for no  $y \in \mathcal{N}(x)$  is  $y \leq m$ .

But m is then minimal also in X, hence  $\{m\}$  is open.

From this follows: The set of open points in X is dense in X.

# Summary

 The join operator and decomposition of topological spaces into indecomposable building blocks is a tool to analyse local properties of smallest-neighborhood spaces.

# Summary

- The join operator and decomposition of topological spaces into indecomposable building blocks is a tool to analyse local properties of smallest-neighborhood spaces.
- For many results we have to assume local finiteness, that is, finite neighborhoods.

# Summary

- The join operator and decomposition of topological spaces into indecomposable building blocks is a tool to analyse local properties of smallest-neighborhood spaces.
- For many results we have to assume local finiteness, that is, finite neighborhoods.
- Next project: Understand the possibilities (or impossibility) of creating a (reasonable) digital Khalimsky manifold concept.